Last Time: Curl and Divergence

Curl (7) = VxV | div(7) = V.V

<P,Q,R>

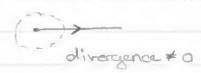
Prop: O curl (Vf) = 3 (2) div(curl(V)) = 0

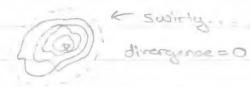
Interpretations of Curl and Divergence

O Curl measures "how swirty is the V.f."?

Curl (7) is always "swirty".

divergence measures "does the v.f. tend to push points away from a little open region?"





Ex.

Consider v.f.  $\langle P(x,y), Q(x,y), 0 \rangle = \vec{1}$ .  $curl(\vec{3}) = del \begin{bmatrix} \vec{1} & \vec{3} & \vec{k} \\ \frac{2}{3x} & \frac{2}{3y} & \frac{2}{3z} \\ P & Q & 0 \end{bmatrix}$ 

= <-Qz,+Pz, Qx-Py> = <0,0,0,0x-Py>

$$= \langle 0, 0, 0 \times - P_{y} \rangle$$
  
=  $\langle 0, 0, \frac{30}{3x} - \frac{3P}{3y} \rangle$ 

Recasting Green's Theorem w/ Vector fields:

Let  $\vec{v} = \langle P(x,y), Q(x,y), 0 \rangle$ , have ets partial derivatives on some open region  $R \subseteq R^2$  and containing closed region D we piecewise - smooth simple, closed boundary curre. Then  $D \text{ SD curl}(\vec{v}) \cdot \vec{k} dA = \text{ SO } \vec{v} \cdot d\vec{r}$  and  $D \text{ SO } \vec{v} \cdot (y'(z)\vec{v} - x'(z)\vec{r}) \cdot \vec{k} dA = \text{ SO } \vec{v} \cdot d\vec{r}$  and  $D \text{ SO } \vec{v} \cdot (y'(z)\vec{v} - x'(z)\vec{r}) \cdot \vec{k} dA = \text{ SO } \vec{v} \cdot d\vec{r}$  and  $D \text{ SO } \vec{v} \cdot (y'(z)\vec{v} - x'(z)\vec{r}) \cdot \vec{k} dA = \text{ SO } \vec{v} \cdot d\vec{r}$ 

Why: O carl (7) = <0,0, 32 - 34 ), so carl (7). = = = = = 34 - 34 : 880 curl(7). kdA = 880 (30 -30) dA Green's Theorem -> = Sop Pax + Ody = Stoa (P(x)y)x'(t) + Q(x)y)y'(t) dt = ft=a < P,Q,0> - <x',y', 2'>dt = Soo J. dz ω=<-Q,P,0> @ SSD div (7) dA = SSD (32 + 30) dA = 86 (30 - 3(-0)) dA ↔ 86 (3 - 3 )dA = for - Odx + Pdy ↔ Jan Adx + Bdy = St=a (-0x'+Py')dt = St=a (Py'-Qx') oft = St=a < P,Q> · < y',-x' > dt = 800 J. (g(t) - x'(t)) Tr'(t) ds NB: These two ways of rewriting Green's Theorem w/ @ divergence 1 Curl are jumping points for generalizing Green's Theorem Divergence Theorem Stokes's Theorem Not on Exam 3, but on the final 7 6.6: Parametric Surfaces Idea: Generalize space curves to have dimension 2 ... Des: A parametric surface in 3-space is given by vector function 3 (u,v) = (x(u,v),y(u,v), Z(u,v)) on some domain DSR. Ex. The Euclidean Plane sits on TR3 as a parametric surface 3(x,y) = < x,y,0)

Ex.

Every plane T in  $\mathbb{R}^3$  can be parameterized by  $\vec{S}(a,b) = a\vec{u} + b\vec{v} + \vec{\omega}$  for suitable vectors  $\vec{u}_1 \vec{v}_1 \vec{\omega}$ , on  $D = \mathbb{R}^2$ 



I.e. 3 (a,b) = < u,a + V1b + w, u2a + V2b + w2, u3a + V3b + w3)

Ex.

The sphere of radius +>0 is parameterized by

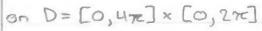
\$(0, 4) = < rsin(4) cos(0), rsin(4) sin(9), rcos(4) > on D=[0,27] × [0,77].



Ex.

The torus has parameterization

3 (0,4) = < (2+sin(0))cos(4), (2+sin(0))sin(4),cos(0))





Donut, aka torus

Ex.

Parametrize the parabdoid == x2+242

UB: There is no one parameterization of a surface ...

500: 3(x,y)= <x,y,x2+2y2> on D=R2

501. D: 3(1,0)= < rcos(0), rsin(0), (roos(0))2+2(rsin(0))2>

= < (cos(0), rsin(0), r2(1+sin2(0))> on D=[0,00) x [0,20]

Soi. B: 3(1,0) = < 12 (0040), 13in(0), 22) on D= [0,00) x [0,27]

Ex.

A surface of revolution (about x-axis) be obtained for a (x) = x+1

function f(x) via

3 (x,0) = <x,f(x)cos(0),f(x)sin(0))

on D = dom (f) x [0, 27].